

1

2	
3	Management Component Transport Protocol (MCTP)
4	Overview
5	White Paper
6	
7	Version 1.0.0a
8	Status: Informational
9	Publication Date: July, 2007
10	DSP2016

- 11 Copyright © 2007 Distributed Management Task Force, Inc. (DMTF). All rights reserved.
- 12 DMTF is a not-for-profit association of industry members dedicated to promoting enterprise and systems manage-
- 13 ment and interoperability. Members and non-members may reproduce DMTF specifications and documents for uses
- 14 consistent with this purpose, provided that correct attribution is given. As DMTF specifications may be revised
- 15 from time to time, the particular version and release date should always be noted.
- 16 Implementation of certain elements of this standard or proposed standard may be subject to third party patent rights,
- 17 including provisional patent rights (herein "patent rights"). DMTF makes no representations to users of the standard
- 18 as to the existence of such rights, and is not responsible to recognize, disclose, or identify any or all such third party
- 19 patent right, owners or claimants, nor for any incomplete or inaccurate identification or disclosure of such rights,
- 20 owners or claimants. DMTF shall have no liability to any party, in any manner or circumstance, under any legal the-
- 21 ory whatsoever, for failure to recognize, disclose, or identify any such third party patent rights, or for such party's
- 22 reliance on the standard or incorporation thereof in its product, protocols or testing procedures. DMTF shall have no 23
- liability to any party implementing such standard, whether such implementation is foreseeable or not, nor to any
- 24 patent owner or claimant, and shall have no liability or responsibility for costs or losses incurred if a standard is 25 withdrawn or modified after publication, and shall be indemnified and held harmless by any party implementing the
- 26 standard from any and all claims of infringement by a patent owner for such implementations.
- 27 For information about patents held by third-parties which have notified the DMTF that, in their opinion, such patent
- 28 may relate to or impact implementations of DMTF standards, visit
- 29 http://www.dmtf.org/about/policies/disclosures.php.

31	
32	Version 1.0.0a
33	Publication Date: June, 2007
34	DSP2016
35	Status: Informational

36 Abstract

37 The Management Component Transport Protocol (MCTP) is a protocol defined by the DMTF Platform

- 38 Management Component Intercommunications sub-team of the DMTF Pre-OS Workgroup. MCTP is
- 39 designed to support communications between different intelligent hardware components that make up a
- 40 platform management subsystem that is provides monitoring and control functions inside a managed sys-
- 41 tem.
- 42 This document provides an overview of the architectural goals and general operation of MCTP.
- 43

44 **Table of Contents**

45	Ab	stract		3
46	1	Intro	duction	6
47		1.1	Target Audience	6
48		1.2	Related Documents	6
49		1.3	Terminology	6
50		1.4	Acronyms and Abbreviations	7
51	2	MCT	TP Highlights	8
52		2.1	Goals	8
53		2.2	MCTP Specification Documents	9
54			2.2.1 Common Specifications	9
55			2.2.2 Transport Binding Specifications	9
56			2.2.3 Message Type Specifications	9
57	3	MCT	TP Technology Overview1	0
58		3.1	MCTP Base Protocol	0
59		3.2	MCTP Endpoints and EIDs1	0
60		3.3	MCTP Busses 1	
61		3.4	MCTP Bus Owners and Bridges 1	
62		3.5	MCTP Packet Routing	
63		3.6	Message Types 1	
64		3.7	MCTP Control Messages and Control Protocol	
65		3.8	Transport Binding Specifications1	.2
66	4	Exar	nple MCTP Topology 1	3
67	5	Cond	clusion1	5
68				
69	Li	st o	f Figures	

70	Figure 1 - Example MCTP Topology	3
----	----------------------------------	---

71 **1** Introduction

- 72 The lack of standard interfaces among platform management components impedes the ability for
- 73 platform developers to be able quickly and economically develop and deploy platform manage-
- 74 ment subsystems that can be accessed using DMTF Common Information Model (CIM) Profiles
- 75 and access protocols. The DMTF Platform Management Component Intercommunications
- 76 (PMCI) sub-team of the DMTF Pre-OS Workgroup seeks to address this problem by defining
- interfaces and data models that facilitate interoperability and interchangeability among platform
- 78 management components, enabling devices from different vendors to be more readily linked to-
- 79 gether into a cohesive manageability subsystem.
- 80 The Management Component Transport Protocol (MCTP) supports the PMCI goals by defining
- 81 a media-independent transport protocol that enables communications between different intelli-
- 82 gent hardware components that make up a platform management subsystem that provides moni-
- 83 toring and control functions inside a managed system.

84 1.1 Target Audience

85 The intended target audience for this document is readers that develop or utilize platform man-

86 agement subsystems that are formed using management controllers and intelligent management

87 devices and are interested in obtaining an overview of the MCTP specifications that define a

88 common intercommunication mechanism for those components.

89 **1.2 Related Documents**

- 90 [1] DMTF, <u>DSP0236</u>, Management Component Transport Protocol (MCTP) Base Specification
- 91 [2] DMTF, <u>DSP0237</u>, Management Component Transport Protocol (MCTP) SMBus / l²C
 92 Transporting Binding Specification
- 93 [3] DMTF, <u>DSP0238</u>, Management Component Transport Protocol (MCTP) PCIe VDM Trans 94 port Binding Specification
- 95 [4] DMTF, <u>DSP0239</u>, Management Component Transport Protocol (MCTP) IDs and Codes
- 96 [5] DMTF, <u>DSP2014</u>, Systems Management Architecture for Mobile and Desktop Hardware
 97 White Paper

98 **1.3 Terminology**

99

Term	Definition
ATCA	Advanced Telecommunications Computing Architecture. ATCA is a specifica- tion effort PCI Industrial Computer Manufacturers Group (PICMG). Known as AdvancedTCA™ (also often abbreviated as ATCA), the official specification designation is PICMG 3.x. AdvancedTCA requirements of "carrier grade" communications computer systems. ATCA includes specifications for platform management subsystem elements within and between blades in a blade- based computer chassis.
l ² C	Name of a multi-master, two-wire, serial bus originally developed by Philips Semiconductor.
In-Band	Management that operates with the support of hardware components that are critical to and used by the operating system

Term	Definition
Intelligent Management Device	A management device that is typically implemented using a microcontroller and accessed through a messaging protocol. Management parameter access provided by an IMD is typically accomplished using an abstracted interface and data model rather than through direct "register level" accesses.
IPMB	Intelligent Platform Management Bus. Name for the architecture, protocol, and implementation of an I2C bus that provides a communications path between "management controllers" in IPMI -based systems.
IPMI	A set of specifications defining interfaces and protocols originally developed for server platform management by the IPMI Promoters Group: Intel, Dell, HP, and NEC
Manageability Access Point (MAP)	A collection of services of a system that provides management in accordance to specifications published under the DMTF Server Management Architecture for Server Hardware initiative.
Management Controller	A microcontroller or processor that aggregates management parameters from one or more management devices and makes access to those parameters available to local or remote software, or to other management controllers, through one or more management data models. Management controllers may also interpret and process management-related data, and initiate manage- ment-related actions on management devices. While a native data model is defined for PMCI, it is designed to be capable of supporting other data models, such as CIM, IPMI, and vendor-specific data models. The microcontroller or processor that serves as a management controller can also incorporate the functions of a management device.
Managed Element	The finest granularity of addressing which can be the target of commands or messages, or a collection thereof.
Out-of-Band	Management that operates with hardware resources and components that are independent of the operating systems control
RMII	A reduced signal count MAC to PHY interface, based on the IEEE Media In- dependent Interface (MII), which was specified by the RMII Consortium (3Com Corporation; AMD Inc.; Bay Networks, Inc.; Broadcom Corp.; National Semi- conductor Corp.; and Texas Instruments Inc.)
SMBus	Name of a multi-master, two-wire, serial bus specified by the Smart Battery Systems Implementer's Forum.

1001.4Acronyms and Abbreviations

101

Term	Definition
MAP	Manageability Access Point
MCTP	Management Component Transport Protocol
PCIe	PCI Express™
PMCI	Platform Management Component Intercommunications. The name of the sub-team of the DMTF Pre-OS Working Group that developed the MCTP and other platform management hardware -related specifications.
USB	Universal Serial Bus

102 2 MCTP Highlights

103 The Management Component Transport Protocol (MCTP) is a media-independent protocol for 104 intercommunication among intelligent devices within the platform management subsystem of a 105 managed computer system. This protocol is independent of the underlying physical bus proper-106 ties, as well as the "data-link" layer messaging used on the bus.

107

108 The physical and data-link layer methods for MCTP communication across a given medium are

- 109 defined by companion "transport binding" specifications, such as MCTP over PCIe $\mbox{\ embed{W}}$ Vendor
- 110 Defined Messaging and MCTP over SMBus/ I^2C . This approach enables future transport bindin as to be defined to support additional bases such as USP. DMH, and others without offseting
- 111 ings to be defined to support additional buses such as USB, RMII, and others, without affecting 112 the base MCTP specification.
- 112
- 114 MCTP has been designed to carry multiple types of manageability-related traffic across a com-
- 115 mon medium. The base MCTP specifications define message types for supporting the initializa-
- tion and configuration of MCTP itself, and to support vendor-specific messages over MCTP.
- 117 Other message types, such as message types to support a Platform Level Data Model (PLDM),
- 118 network controller sideband communications, and so on, are planned to be specified in the future
- 119 by the DMTF PMCI workgroup.
- 120

130

An example of a basic platform management subsystem topology that utilizes MCTP is shown inFigure 1 on page 13.

123 **2.1 Goals**

- 124 MCTP has been designed to address the following goals:
- Provide efficient communications between the following parties in a platform management subsystem:
- 127 Management Controllers and Intelligent Management Devices
- 128 Management Controllers and other Management Controllers
- 129 Management Controllers and system firmware (e.g. BIOS)
 - Management Controllers and Network Controllers
- Support multiple media types: for example, SMBus/I²C, PCIe VDM, USB, and others.
- Support multiple message types on a common media.
- Be suitable for different classes of computer system such as server, desktop, mobile, and communications systems.
- Use compact, byte-efficient formats and simple protocols that are suitable for implementation using low-cost microcontrollers.
- Capture and integrate learning's from other management bus protocols such as IPMB,
 SMBus, ATCA, ASF, by providing:
- 139 o Improved addressing
- 140 o Simplified message routing
- 141 Support for device discovery and hot plug devices

- Be cleanly extensible and maintainable
- Provide clear points in the specifications and protocol for supporting new mes sages types, media types, protocol version information, and so on.
- Provide support for Vendor-specific message types to allow value-added func tions to use MCTP as a framework without conflicting with base MCTP messag ing.

148 **2.2 MCTP Specification Documents**

149 MCTP is defined through a set of DMTF specifications. The following documents make up the

150 MCTP specifications:

151 **2.2.1 Common Specifications**

- 152 These documents are the generic documents for the MCTP.
- 153 DSP0236, Management Component Transport Protocol (MCTP) Base Specification
- 154This document describes the aspects of the MCTP, message routing, and MCTP ini-155tialization that are common across all MCTP implementations. The specification con-156sists of three main sections: MCTP base protocol, MCTP Control Protocol, and157MCTP Control Common description
- 157 MCTP Control Commands.
- 158 DSP0239, Management Component Transport Protocol (MCTP) IDs and Codes
- 159This document presents a collection of IDs and codes that are used across the Man-160agement Component Transport Protocol (MCTP) and transport binding specifica-161tions.

162 2.2.2 Transport Binding Specifications

163 These documents describe how MCTP is implemented on a particular physical medium. There 164 are two transport binding specifications as of this writing:

- 165 DSP0237, Management Component Transport Protocol (MCTP) SMBus / l²C Transport
 166 Binding Specification
- 167This document defines how MCTP is carried using SMBus or I^2C as the transport168medium.
- 169 <u>DSP0238</u>, Management Component Transport Protocol (MCTP) PCIe VDM Transport
 170 Binding Specification
- 171This document defines how MCTP is carried using PCI ExpressTM Vendor Defined172Messages (VDMs) as the transport medium.

173 **2.2.3 Message Type Specifications**

- 174 MCTP Message Type specifications define how a particular class of payload is carried using
- 175 MCTP. As of this writing, only MCTP Control and Vendor Defined message types are specified.
- 176 The specification of these message types is incorporated in the MCTP Base Specification rather
- 177 than as separate documents. In the future, message types for carrying traffic such as the PMCI
- 178 Platform Level Data Model will be defined and provided as companion specifications to the pre-
- 179 sent MCTP specification documents.

180 3 MCTP Technology Overview

181 This section provides a more detailed overview of the elements and operation of MCTP.

182 **3.1 MCTP Base Protocol**

- 183 The basic unit of data transfer in MCTP is the "MCTP packet". One or more MCTP packets are
- used to transfer an "MCTP message". The base protocol defines the common fields for MCTP
- 185 packets and how they are used. This includes defining fields such as source and destination address fields, fields that identify which packets belong to a particular MCTP message, and fields
- 186 dress fields, fields that identify which packets belong to a particular MCTP message, and fields 187 that define what type of communication traffic is being carried in the MCTP message. The base
- protocol also defines the processes used for assembling MCTP messages, routing MCTP packets,
- 189 and handling error conditions such as dropped or missing packets.

190**3.2MCTP Endpoints and EIDs**

- 191 An endpoint is the function within a device that terminates the communication protocol of
- 192 MCTP and handles MCTP Control commands. MCTP uses a logical address called the endpoint
- 193 ID (EID) for addressing and routing MCTP packets to and from endpoints.

194 **3.3 MCTP Busses**

- 195 In MCTP a bus is defined as an interconnect between platform components that share a common
- 196 physical layer address space. A bus may be made up of multiple segments. A bus segment is a
- 197 portion of a bus that is electrically separated from other segments that form a bus, but still shares
- a common physical address space with other segments.

MCTP Bus Owners and Bridges

- Each MCTP bus has a bus owner. Bus Owners are responsible for assigning EIDs to any MCTP
 devices on that bus. A bus owner may also have additional media-specific responsibilities, such
 as device discovery and assignment of physical addresses.
- 203
- 204 MCTP Bridges are devices that connect to two or more MCTP busses and are responsible for
- routing MCTP packets between those busses. A Bridge will typically also be the bus owner for at
- least one of the busses to which it connects.
- 207
- MCTP allows multiple bridges, busses, and bus owners to be interconnected to form an "MCTP network". Because bus owners are responsible for assigning EIDs to any devices that are on the
- bus that it owns, MCTP provides a mechanism that enables bus owners to be allocated a pool of
- endpoint IDs that can subsequently be assigned or allocated to other devices. The ultimate source
- of EIDs for the entire MCTP network comes from what is referred to as the "topmost bus
- 213 owner".
- 214
- 215 MCTP bus owners and bridges are also responsible for providing a service that enables resolving
- 216 EIDs into physical addresses so that the originator of an MCTP packet knows what destination
- 217 physical address needs to be used to route a message to a given EID.

218 **3.5 MCTP Packet Routing**

- 219 MCTP packets are routed based on their EIDs. MCTP bridges maintain a set of information re-
- ferred to as the "routing table" that tracks the relationship between the physical addresses and

- bus with which an EID is associated. When an incoming packet is received, this information is
- used to route the packet to the appropriate bus. If the source and target busses use different
- physical media the bridge is also responsible for translating the physical layer formatting of the packet as required by the target medium.
- 225
- The information in the routing table is also used for handling requests to resolve an EID into a
- 227 physical address and to support a capability to query individual bridges and bus owners for their
- routing information. This latter capability provides a way to obtain a snapshot of the MCTP net-
- 229 work's routing configuration.
- 230

The MCTP bridging function simply forwards packets based on endpoint addressing information on a per packet basis. Otherwise, bridging does not interpret message content, or handle message type-specific protocol behavior for routed packets. Bridging does not do intermediate assembly or disassembly of routed packets. Message assembly and disassembly is handled solely by the destination and source endpoints, respectively.

- 236
- 237 MCTP packet routing between busses does not include a broadcast capability, although individ-
- 238 ual busses may support broadcast as required by the particular medium to support device discov-
- ery. This eliminates the complexity of having bridges replicate and transmit packets across mul-
- tiple busses.

241 **3.6 Message Types**

The type of communication payload in an MCTP Message is identified by an enumeration called the "MCTP Message Type". MCTP is designed to be able to carry packets for multiple message

- types across a common communications medium. The MCTP base protocol specification in-
- cludes definition of a message type for MCTP Control messages and message types that support
- 246 Vendor-defined MCTP messages. Other message types, such as a future message type to support
- 247 Platform Level Data Model (PLDM) are defined in separate specifications.
- 248
- Different message types are identified by a message type field that is carried in the header of an MCTP message. The value in this field is an existent in the second seco
- 250 MCTP message. The value in this field is specified in the specification that defines the message
- type. In addition, DSP0239, the Management Component Transport Protocol (MCTP) IDs and
- 252 Codes specification, provides a centralized collection of the message types values defined for
- 253 MCTP.

254 3.7 MCTP Control Messages and Control Protocol

- The MCTP Base Specification includes the definition of a message type for "MCTP control mes-
- 256 sages". These messages are used by bus owners to initialize and maintain the addressing and 257 routing used in an MCTP network. MCTP control messages also include messages to help de-
- termine the basic MCTP messaging capabilities of a endpoint, such as what MCTP version and
- 259 message types it supports. Control messages that initiate or request an action are also referred to
- 260 as "commands".
- 261
- 262 The MCTP Control Protocol defines the format of MCTP control messages and how they are
- 263 delivered and acknowledged. Almost all control messages are delivered using a request / re-
- sponse mechanism where a request message is delivered to a target or "responder" endpoint us-
- 265 ing an MCTP message transfer, and then later the responder delivers a response message back to

- the requester. Response messages provide a positive acknowledgement of the receipt and han-
- 267 dling of the request and return parametric data (if any) according to the request.
- 268
- The control protocol also supports delivering messages as unacknowledged "datagrams" and as broadcasts on the bus. These mechanisms are made available to support control messages that
- 271 can be used for device discovery as required by the medium.
- 272
- 273 The control protocol includes a retry mechanism to help ensure reliable delivery of requests, and
- to cover cases where a responder may be briefly off-line. The control protocol defines fields that
- are used to identify requests and responses, to identify whether a message is a datagram, and to
- 276 identify new instances of requests from retried instances.

3.8 Transport Binding Specifications

- 278 The Transport Binding specifications are documents that describe how MCTP is implemented on
- a particular physical medium. This includes the definition of MCTP packet formatting for the
- 280 medium, source and destination physical addressing handling, physical layer data integrity, and
- 281 medium-specific timing parameters.
- 282
- 283 The transport binding specifications include the definition of physical layer retry mechanisms for
- 284 MCTP packets (if any).

285 4 Example MCTP Topology

The following example illustrates how MCTP can be used within a hypothetical platform management subsystem implementation. More complex topologies, with multi-levels of bridges and greater numbers of busses and devices can be readily supported by MCTP as required.

289



290

291

Figure 1 - Example MCTP Topology

292

295

293 The following table describes the hardware elements that make up the subsystem shown in

294 Figure 1

Element	Description
Bus 1	a PCIe bus that provides a high bandwidth connection between Management Controller D1 and Network Controller D2
Bus 2	an SMBus that connects to the PCI Express slots in the system
Bus 3	an SMBus that provides a separate connection for use by D2 and D4
D1	a microcontroller that provides MCTP bus owner and bridge functions for the motherboard and also provides the intelligence for a DMTF Management Access Point (MAP). (see <u>DSP2014</u>)
D2	a network controller that contains a sideband interface function that enables network traffic to be trans- ferred using MCTP over either bus 1 or bus 2
D3	a PCI Express add-in card that contains sensors (e.g. error status, temperature, and fan sensors)
D4	in this example, D4 represents a management controller that also provides the intelligence for a DMTF Management Access Point (MAP). (see DSP2014)

296

297 In this example, D1 is a management controller that serves as intelligence for a DMTF MAP that

enables system sensors and control functions such as temperature, voltages, fan speeds, power

299 on/off/reset, etc. to be accessed using DMTF CIM data models. Network controller D2 provides

300 the network sideband interface that is used to transfer packets between D1 and a local area net-

- 301 work.
- 302

303 Network controller D2 has two connections: an SMBus connection via bus 3 and a PCIe connec-

tion via bus 1. The SMBus connection is a low-power connection that is available in all system

- 305 power states, but is low-bandwidth (< ~100kbps) while the PCIe connection is higher bandwidth,
- but is only available when the system is fully powered and after the BIOS/OS have initialized
- 307 PCIe. The SMBus connection thus provides a way to communicate with the MAP while the sys-
- tem is powered down or in a sleep state, and the PCIe connection provides a connection that can deliver performance for functions such as madia radiraction. Firmware under a state and the state of the
- deliver performance for functions such as media redirection, firmware updates, and so on, whenthe system is powered up.
- 311
- 312 D3 represents a PCIe add-in card that is connected to an SMBus, bus 2, that is routed across the
- 313 PCIe connectors in the system. In this example, bus 2 is separated from bus 3 in order to prevent
- any possibility that erroneous traffic or hardware errors on bus 2 will affect the SMBus commu-
- 315 nication between D4, D2, and D1.
- 316
- 317 D4 represents a management controller that is dedicated to monitoring and control functions that
- 318 are related to thermal management of the system. It uses the MCTP connections to access tem-
- 319 perature sensors and fan speed data maintained by D1, D3, and itself.
- 320

321 **5 Conclusion**

- 322 MCTP provides a common, flexible, media-independent, and byte-efficient protocol to enable 323 the interconnection of devices from multiple vendors within a platform management subsystem.
- 324 MCTP supports message types that will be defined by the DMTF PMCI workgroup to provide
- 325 common access and abstraction of the low-level monitoring and control functions within the
- 326 platform management subsystem that will in turn support the representation and access of plat-
- 327 form manageability functions via higher level DMTF CIM data models, transports, and profiles.